

Lettuce Yield Prediction: ElasticNet Regression Model (EINetRM) for Indoor Aeroponic Vertical Farming System

Original Scientific Paper

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Abstract – Indoor aeroponic vertical farming systems have revolutionized agriculture by allowing efficient use of space and resources, eliminating the need for soil. These systems improve crop productivity and growth rates. However, accurately predicting lettuce yield in aeroponic environments remains a complex task due to the intricate interactions between environmental, nutrient, and growth parameters. This work aims to address these issues by integrating advanced sensor technologies with ElasticNet Regression Model (EINetRM) for its hybrid L1 and L2 regularization capabilities, handling multicollinearity and feature selection problems effectively in order to develop a reliable yield prediction framework. The predictive results showcases that the EINetRM model forecasts lettuce yield with high accuracy of 92% and less error score (RMSE) of 2.28 using a comprehensive dataset from a sensor-equipped indoor aeroponic system. Also, the results demonstrate the superior predictive power of EINetRM in capturing complex variable relationships, enhancing yield prediction reliability.

Keywords: indoor aeroponic vertical farming, elasticnet regression, machine learning, yield prediction

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1. INTRODUCTION

Machine learning applications in lettuce production is revolutionizing the farming, improving efficiency, adaptability, and sustainability is being examined in this research study. This study highlights the integration of convolutional neural networks (CNNs) and YOLO-based models in lettuce crop cultivation which involves pest and disease diagnosis, precision spraying, pesticide residue detection, crop condition monitoring, growth stage classification, yield prediction, weed management, and irrigation and fertilization management [1]. Another research highlights that the advanced Machine learning (ML) techniques are crucial for food security and hydroponic systems, but inconsistent predictions due to diverse features and datasets require further research. Integrating advanced ML

techniques with hydroponic systems holds promise for accurate yield forecasts and sustainability [2]. Artificial intelligence and IoT in aeroponics enable accurate regulation of fertilizer concentrations, misting cycles, temperature, and humidity. The integration of plasma-activated water and plasma-activated mist improves resource efficiency and plant health. Machine learning applications in lettuce production improve efficiency, adaptability, and sustainability [3].

In order to satisfy the increasing demands of the rising population, global food production must quadruple by 2050 [4, 5]. Nevertheless, the present rates of grain growth are insufficient to attain this objective [6]. Climate change impacts agriculture, potentially reducing crop production and increasing food scarcity. With a projected 9 billion global population by 2050, governments

must manage sudden crop availability disruptions [7, 8]. The Food and Agriculture Organization (FAO) reports a significant rise in grain demand and consumption in emerging countries like India between 1964 and 2030, with cereal imports increasing from 39 million tons in 1970 to 130 million tons between 1997 and 1999. This trend is expected to persist and potentially accelerate [9]. Importing conventional crops can lead to food security issues. Precision agriculture requires accurate crop forecasting, but weather conditions influence production. Models for accurate forecasting are needed for informed planning [10, 11]. Forecasting in applied sciences is crucial for precision farming techniques like aeroponic indoor farming. Machine learning techniques are being integrated into marketing software, equipment maintenance, health-monitoring systems, agricultural yield prediction, and soil analysis to improve crop growth and productivity [12].

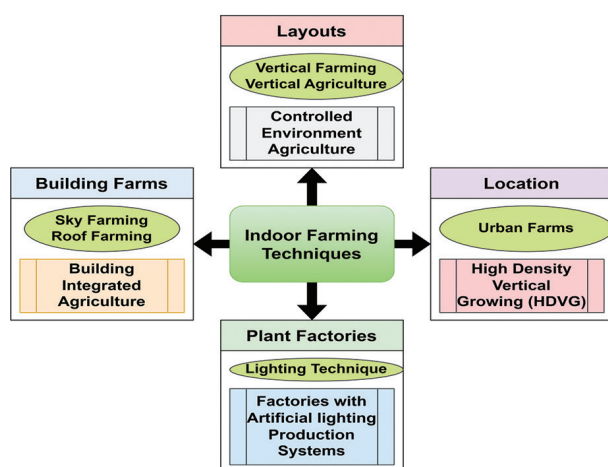


Fig. 1. Various forms of Vertical Farming

This research article provides a detailed description on the lettuce yield prediction with the efficacy of the ElasticNet machine learning regression model. This manuscript is organized in such a way, section-2 deals with the detailed literature survey, section-3 with the methodology involved, section-4 with the implementation results and discussions and finally, section-5 and section-6 with the conclusion and future scope of the research that leads to the further enhancement of the proposed work.

2. LITERATURE SURVEY

Using precision farming techniques integrated with the applications of machine learning algorithms, the researchers have analyzed, implemented and developed the crop prediction models in an effective manner.

Historically, crop-cutting experiments were used to quantify agricultural yield, but it's time-consuming and requires human labor. Currently, artificial neural networks, LASSO-Least Absolute Shrinkage and Selection Operator, and ELNET are used for predicting yields [13-17]. Sridhara *et al.* [18] used the LASSO, ENET, PCA, ANN, and SMLR

methodologies for predicting the Sorghum harvest. The researchers found that the developed artificial neural network (ANN) model outperformed the ENET regression model in estimating the yield of wheat crop.

Raja and Shukla [19, 20] used an Extreme Learning Machine (ELM) and hybrid grey-wolf-optimization Artificial Neural Network (ANN) models to get a more accurate forecast of the final bearing capacity and settlement of a geosynthetic-reinforced sandy soil.

Vertical farming, an innovative agricultural method, is attracting interest due to its capacity to enhance crop productivity per unit of land area [21, 22]. Nevertheless, the increase in expenses may have an adverse effect on profitability. This novel agricultural system tackles issues such as population expansion, limited cultivable area, and environmental limitations. Vertical farming efficiently utilizes space, minimizing the need for land and development in urban areas, while also catering to the increasing need for organic food [23]. Nevertheless, the presence of obstacles in sensor technologies, inventive cultivation approaches, energy optimization, and automation is anticipated to propel progress towards more effective production systems.

Modern technologies and sensors are used in vertical farming to keep an eye on the growing environments and make sure they are perfect for food growth, health, and development [24, 25]. This makes it easier to control energy and use resources more efficiently. Vertical farming is better for the earth than traditional farming because it increases food output and reduces trash [26]. However, it can be hard to combine sensors, control systems, and machine learning methods because they need complex robotics and data management systems.

Vertical farming technology is changing quickly, with a focus on gathering and analyzing data to get the best crop response [27]. This trend is good for the environment, society, and the economy [28, 29] and it looks like it will help keep food fresh in cities. Vertical farming has shown promise for growing a number of different crops, but more study is needed to make it more efficient and cost-effective. It has a lot of promise, but more study is needed to successfully apply it.

A lot of research has been done on different aspects of vertical farming, such as its types [21], how it works [28], how to control the environment and make the best use of resources [25, 30], how to build a smart indoor farm, sensing technologies, trends, and engineering challenges [31].

AI is a powerful computer program that lets computers learn from their mistakes, adapt to new information, and do jobs like people [32]. Vertical farming is a great example of how technology has changed the way food is grown [33]. AI, which is driven by machine-learning algorithms, looks at data and makes choices. It tracks plant growth, improves weather conditions, and makes the best use of resources [32]. AI finds trends and pre-

dicts plant health by looking at data from physical and image sensors [34]. This helps farmers make smart choices and get the most crops.

Recent technological advances are being used in vertical farming to lower costs and protect the environment [35]. AI is very important for keeping an eye on food growth and making output better. Color pictures are used for plant phenotyping under artificial lighting, which lets growers keep an eye on and improve crop growth all the time [36]. Hwang *et al.* [34] created an image-based system to track the growth of crops, and Vorapatratorn *et al.* [37] created an AI-powered system for plant farms to automatically run their operations. Crop-growth records from multiple planting rounds are saved and used to train machine-learning models for automatic plant growth [31]. Rizkiana *et al.* [38] used resilient backpropagation ANNs to guess how tall plants would get, taking into account external factors and the heights of the plants at the start. They did this by growing cabbage in a plant workshop.

A machine-vision method was used by Story *et al.* [39] to find cabbage grown in gardens suffers from deficiency of the essential nutrient called calcium. To showcase the difference between healthy and nutrient-deficient plants, they used a gray-level co-occurrence matrix and dual segmentation regression analysis. A group of researchers led by Hao [40] created a multi-scale hierarchical convolutional neural network (MFC-CNN) design to measure the amount of stress in leaves. Sun *et al.* [41] used a CNN design to collect features from RGB pictures and sensor data to figure out how much water plants were losing. A study by Gozzovelli *et al.* [42] used WGAN and a deep CNN architecture to identify the lettuce plants that were stressed by tip-burn.

AI is revolutionizing vertical farming by improving crop productivity, resource allocation, and automation, but small and medium-sized farms face challenges like high costs associated with collecting and analyzing extensive data from sensors and cameras [32, 43]. The absence of a common software platform may impede the incorporation of AI algorithms [33, 36]. In addition, the use of AI gives rise to issues about privacy and security, particularly in relation to the handling of sensitive data pertaining to crops, farmers, and customers particularly lettuce crops [42, 44].

Data quality challenges such as sensor noise, environmental unpredictability, and human error might impede the accuracy and effectiveness of AI in vertical farming [45, 46]. The process of training and implementing AI models might require a significant amount of resources, particularly for farms that are small or medium-sized. Gaining insight into the decision-making processes of AI models is essential for ensuring transparency and maintaining food safety [47, 45]. Ensuring fairness and accuracy in AI models necessitates the mitigation of bias [40, 44]. Notwithstanding these difficulties, AI has the capacity to transform vertical farming, enhancing its efficiency, productivity, and sustainabil-

ity. Vertical farming may enhance global food security, resource conservation, and environmental stewardship by effectively tackling these challenges and improving AI approaches [31].

3. METHODOLOGY

3.1. ELASTIC-NET REGRESSION FOR LETTUCE CROP YIELD PREDICTION

Lettuce, a popular leafy green herb, is a popular choice due to its health benefits. Aeroponic lettuce can be grown in a controlled environment with nutrient solution sprays. However, yield prediction of lettuce crop in conventional and precision farming is crucial. Machine learning has emerged as a solution for predicting lettuce crop yield effectively. The Elastic-Net (ENet) regression algorithm is chosen for this work, which is a balanced fitting of the dataset, combining LASSO and RIDGE regularization algorithms. This algorithm is chosen for its ability to handle high-dimensional data, handle noise and outliers, optimize hyper-parameters, adapt to new data, make decisions, and provide statistical insights on prediction results. High variance algorithms like decision trees and KNN are examples of high bias.

3.2. MATHEMATICS BEHIND ELASTICNET REGRESSION

Multiple Linear Regression involves more than one independent variable and one dependent variable. It is mathematically represented as,

$$Y = \beta_0 + \beta_1 X_1 + \beta_2 X_2 + \dots + \beta_n X_n \quad (1)$$

where, Y is the dependent variable, X_1, X_2, \dots, X_n are the independent variables, β_0 is the intercept and $\beta_1, \beta_2, \dots, \beta_n$ are the slopes.

The main goal of the algorithm is to find the best fit line equation that can predict the values based on the independent variables. In regression, set of records (dataset) are present with X and Y values and these values are used to learn a function so that to predict Y from an unknown X this learned function can be used. So here, to find the value of Y , a function is required that predicts continuous Y in the case given X as independent features.

In order to best fit line in linear regression, its not easy to get it easily in real life cases so we need to calculate errors that affects it. These errors to be calculated to mitigate them. Thus, the equation for calculating the error function or cost function is represented as,

$$J = \sum_{i=1}^n (\hat{y}_i - y_i)^2 \quad (2)$$

where, J is the error function, \hat{y}_i is the predicted values and y_i is the actual values.

The purpose is to determine the optimal values for the intercept θ_0 and the coefficient of the input feature θ_2 providing the best fit line for representing this relationship,

$$\hat{y}_i = \theta_0 + \theta_2 x_i \quad (3)$$

In order to reduce the error function, the parameter values need to be updated. The technique behind this is to start θ_1 and θ_2 with random values and iteratively update until reaching the minimum error or cost.

So the cost function with respect to θ_1 ,

$$J_{\theta_1} = \frac{\partial(\theta_1, \theta_2)}{\partial \theta_1} \quad (4)$$

$$= \frac{\partial}{\partial \theta_1} \left[\frac{1}{n} \sum_{i=1}^n (\hat{y}_i - y_i)^2 \right] \quad (5)$$

$$= \frac{1}{n} \left[\sum_{i=1}^n 2(\hat{y}_i - y_i) \left(\frac{\partial}{\partial \theta_1} (\hat{y}_i - y_i) \right) \right] \quad (6)$$

$$= \frac{1}{n} \left[\sum_{i=1}^n 2(\hat{y}_i - y_i) \left(\frac{\partial}{\partial \theta_1} (\theta_1 + \theta_2 x_i - y_i) \right) \right] \quad (7)$$

$$= \frac{1}{n} \left[\sum_{i=1}^n 2(\hat{y}_i - y_i) (1 + 0 - 0) \right] \quad (8)$$

$$= \frac{1}{n} \left[\sum_{i=1}^n 2(\hat{y}_i - y_i) \right] \quad (9)$$

$$J_{\theta_1} = \frac{2}{n} \left[\sum_{i=1}^n (\hat{y}_i - y_i) \right] \quad (10)$$

Similarly, for finding J_{θ_2} , the equation is represented below.

$$J_{\theta_2} = \frac{2}{n} \left[\sum_{i=1}^n (\hat{y}_i - y_i) x_i \right] \quad (11)$$

Hence, finding the coefficients of a linear equation that best fits the training data is the objective of the linear regression. The respective intercept and coefficient X will be if α is the learning rate.

$$\theta_1 = \theta_1 - \alpha(J_{\theta_1}) \quad (12)$$

$$= \theta_1 - \alpha \left[\frac{2}{n} \left[\sum_{i=1}^n (\hat{y}_i - y_i) \right] \right] \quad (13)$$

Similarly,

$$\theta_2 = \theta_2 - \alpha(J_{\theta_2}) \quad (14)$$

$$= \theta_2 - \alpha \left[\frac{2}{n} \left[\sum_{i=1}^n (\hat{y}_i - y_i) x_i \right] \right] \quad (15)$$

Since, the Elastic Net model is also a linear regression model that incorporates all the functionalities of

multiple linear regression model. In addition, it also embeds a composite penalty term including both L_1 (Lasso) and L_2 (Ridge) regularization techniques. The objective function of Elastic Net is the sum of the L_1 and L_2 penalty terms, which are added to the ordinary least squares (OLS) objective function. The Elastic Net objective function is expressed in a generic form as follows:

$$Objective = \sum_{i=1}^N (y_i - \hat{y}_i)^2 + \alpha (\lambda_1 \sum_{j=1}^p |\beta_j| + \lambda_2 \sum_{j=1}^p \beta_j^2) \quad (16)$$

where, N is the number of observations; y_i is the actual output for observation i ; \hat{y}_i is the predicted output for observation i ; p is the number of features (predictors); β_j is the coefficient of feature j ; α is the elastic net mixing parameter, controlling the balance between L_1 and L_2 regularization; λ_1 is the L_1 regularization strength; λ_2 is the L_2 regularization strength.

The Elastic Net algorithm aims to find the values of β_j that minimize this objective function. The regularization terms $(\lambda_1 \sum_{j=1}^p |\beta_j| + \lambda_2 \sum_{j=1}^p \beta_j^2)$ help prevent overfitting by penalizing large coefficient values. The mixing parameter α allows you to control the trade-off between L_1 and L_2 regularization.

When $\alpha=0$, the Elastic Net reduces to Ridge regression, and when $\alpha=1$, it reduces to Lasso regression.

The Elastic Net approach is particularly useful when dealing with datasets where many features are correlated, as it can select groups of correlated features together (similar to Lasso) while still providing some of the shrinkage properties of Ridge. This makes Elastic Net a versatile choice for feature selection and regularization in linear regression models.

4. FLOW DIAGRAM, IMPLEMENTATION RESULTS AND DISCUSSIONS

The results and discussions section deals with the detailed notes on various phases from dataset collection to the comprehensive evaluation of the experimental results produced during the implementation of improved ElasticNet regression model on the aeroponic lettuce crop yield estimation as shown in Fig. 2.

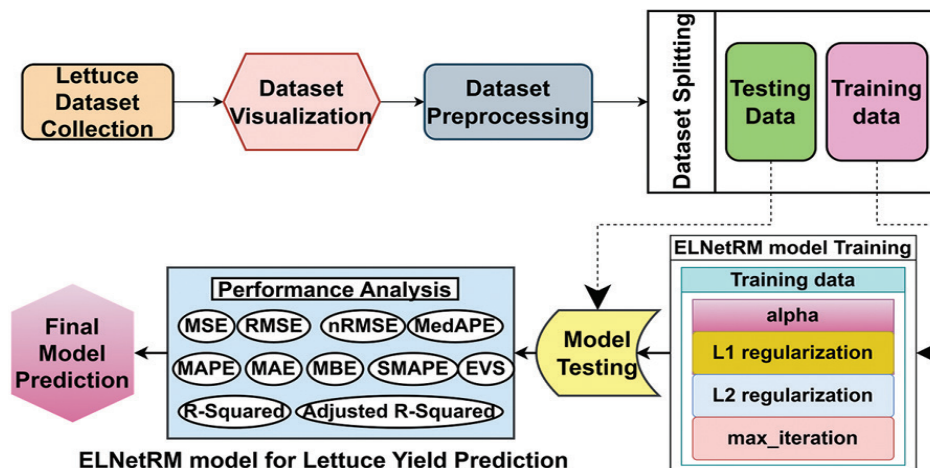


Fig. 2. Architecture diagram of Lettuce Yield prediction using ElnetRM model

4.1. DATASET COLLECTION AND VISUALIZATION

Lettuce growth dataset have been collected from the aeroponic farming Centre for a cycle of 45-60 days. The sample dataset is shown in Fig. 3.

dataset.head()

	pH	TDS	Temperature	EC	Turbidity	Humidity	Light	Growth	Yield
0	6	150.0	28.0	0.29	197.0	55.023	9.7	1.0	20.453
1	6	953.0	27.0	1.72	196.0	85.023	9.7	2.0	21.876
2	6	898.0	27.0	0.28	195.0	115.023	9.7	3.0	23.000
3	6	892.0	27.0	1.34	194.0	145.023	9.7	4.0	27.521
4	6	819.0	27.0	1.84	193.0	175.023	9.7	5.0	30.000

Fig. 3. Sample lettuce growth dataset

There are nine different lettuce features were utilized for training the EInetRM model. All the parameters listed here are related to the indoor or controlled environment agriculture; they are nutrient solution characteristics such as power of hydrogen (pH), total dissolved salts (TDS), electrical conductivity (EC), turbidity and related to the crop growth ambience namely, temperature, humidity, light, growth and yield.

In order to better understand the lettuce datasets utilized for the implementation process, the datasets

were visually represented in the form of pictures. Fig. 3 showcases the distribution plot of the parameter pH with respect to the other input variables.

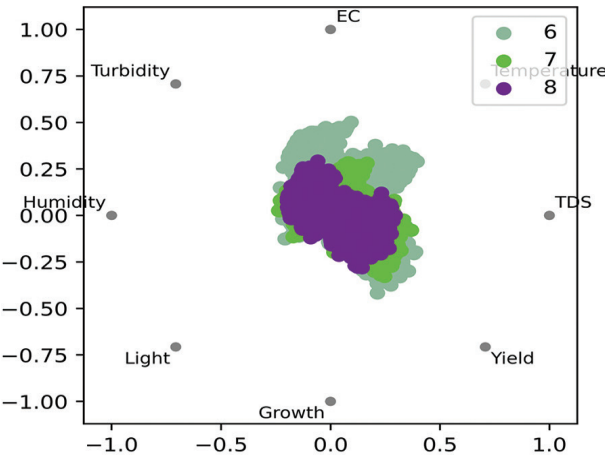


Fig. 4. Distribution Plot of pH parameter

Though there are multiple number of visualization plots are available, histogram technique (bootstrap distribution) was highly utilized to represent the features in an individual manner or as a whole. Fig. 5 showcases the distribution of lettuce growth parameters as separate plots in such a manner that one feature do not collide with another.

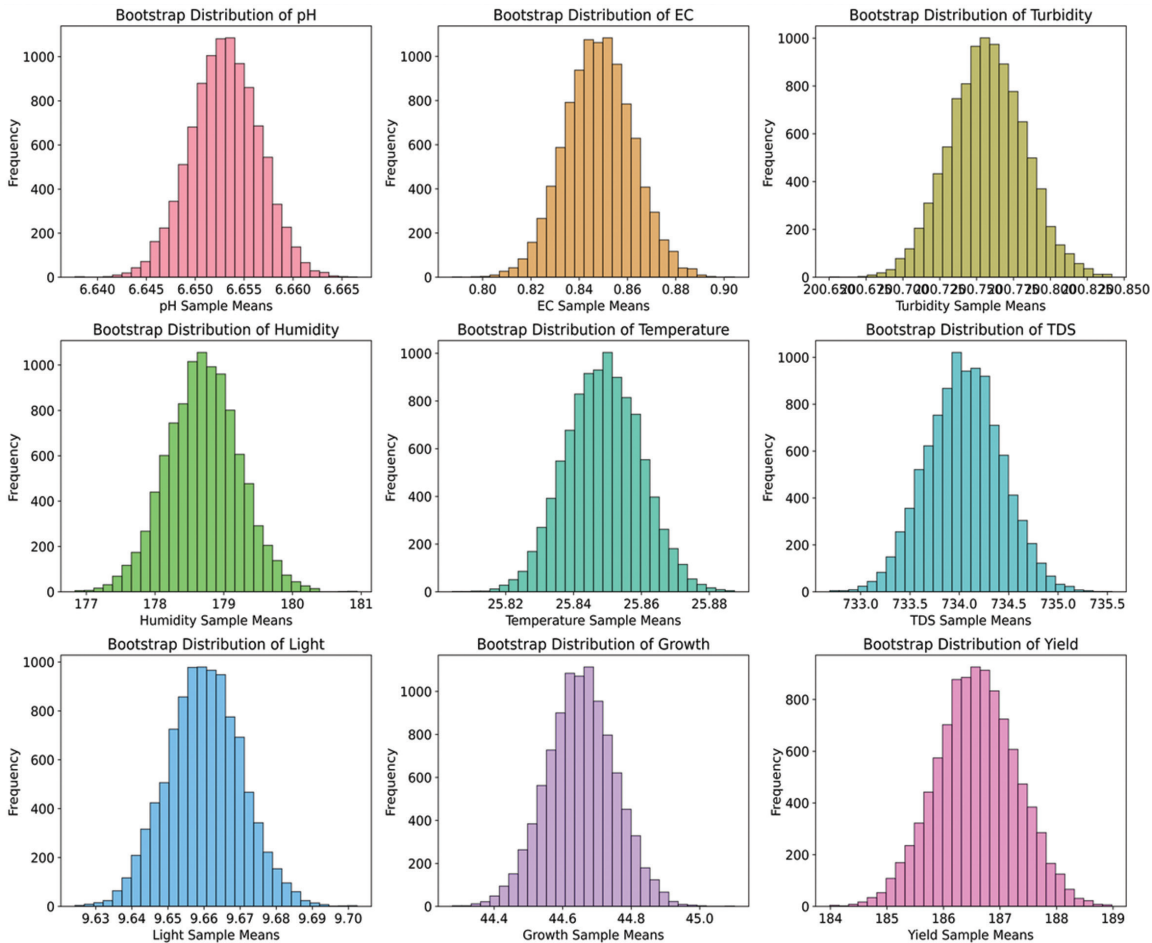


Fig. 5. Bootstrap Distribution Plot of lettuce growth parameters

4.2. PREPROCESSING TOWARDS MODEL TESTING

One of the most important steps before training any machine learning models is preprocessing. Here, the authors have utilized the data cleaning technique called removal of outliers in order to achieve high yield prediction accuracy.

Fig. 6. Represents the boxplot visualization of the original dataset size comprising of 225792 features [25088

rows multiplied with 9 columns]. One of the foremost used preprocessing technique is the removal of outliers, which are being removed from the original dataset with the help of Inter Quartile Range (IQR) method. The features which does not fall within the quartiles i. e within the specified inliers between 25th and 75th quartiles were neglected during the model training.

Once the outliers are identified and removed (cleaned), once again the preprocessed dataset were visualized in Fig. 7.

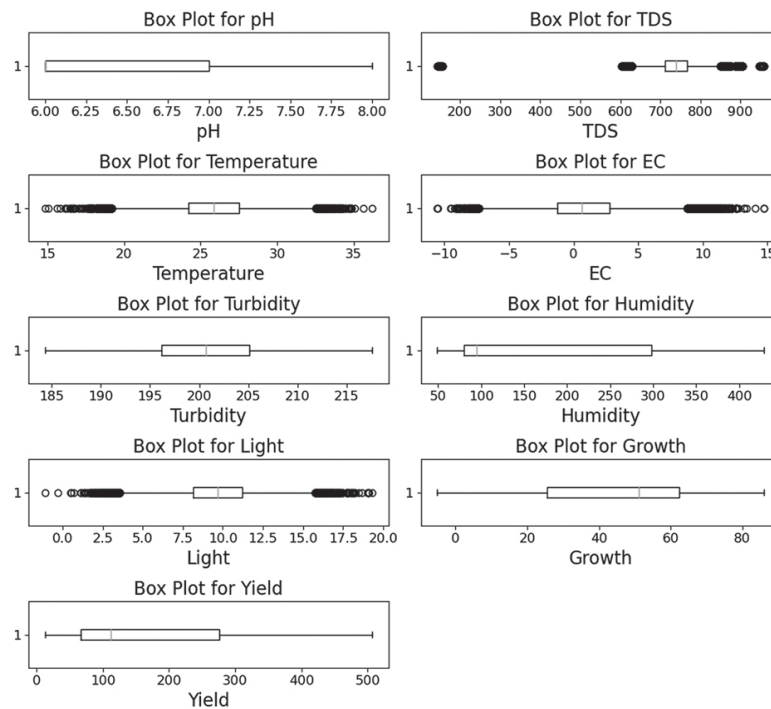


Fig. 6. Boxplot representing dataset with outliers

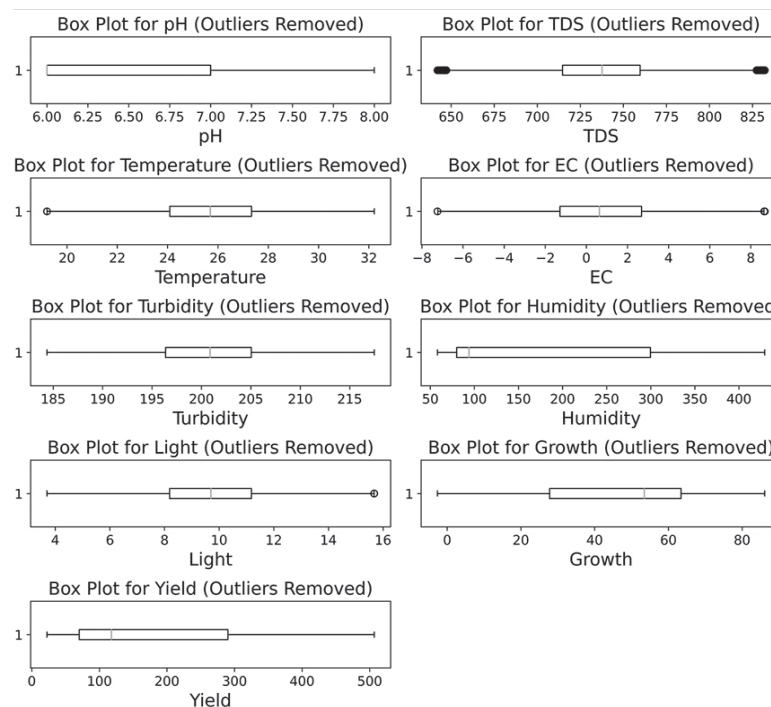


Fig. 7. Boxplot representing dataset without outliers

After preprocessing, the size of the dataset size is reduced to 205251 features i.e [225792-20541 outlier features=205251 features].

4.3. FEATURE SELECTION, DATASET SPLITTING, HYPERPARAMETER TUNING, MODEL TRAINING AND TESTING

Once the dataset is being preprocessed, the core part of the machine learning implementation begins to pro-

cess. The initial step is to select the certain set of lettuce growing features such as pH, EC, light, turbidity, temperature, TDS, turbidity, humidity and growth.

All these growing factors were considered as the independent variables. When the values of these individual crop growth variables changes, it has the significant impact on the lettuce cultivation. The strength and nature of their interrelationships with each other and the output variable can be graphically represented through the correlogram image as represented in Fig. 8.

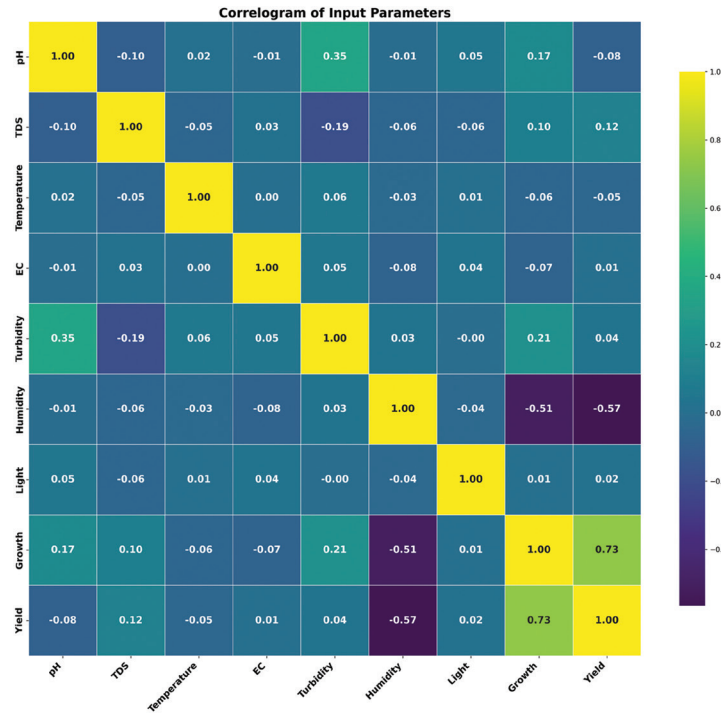


Fig. 8. Correlation diagram of input variables

The next step is the dataset splitting where the pre-processed dataset was split into training and testing datasets in the ratio of 80:20 (where 80% of data utilized for training and 20% of data utilized for testing) for efficient model building.

Once the splitting process is done, the training phase starts. The EInetRM model was trained on the lettuce dataset for learning the underlying patterns. The performance is being measured and kept aside. Obviously, for the first time, the performance would be poor which has to fine-tuned for the further improvements in the yield prediction.

So, the hyperparameter tuning process gets initiated. As the ElasticNet regression is the combination of Lasso and Ridge regression, after performing hyperparameter tuning, the values of the regularization parameters such as Alpha and L_{1ratio} are fixed to 0.5 i.e moderate regularization for alpha and equal contribution of $[L_1$ and $L_2]$ penalties.

After the model gets trained with the training dataset, the model is exposed to the testing dataset where the real research work was concentrated to prove the efficiency

of the improved model. Here, hyper-parameter tuning via cross-validation was not utilized as the fixed threshold "0.5" provides the least error metric and higher accuracy.

4.4. PERFORMANCE METRICS USED FOR MODEL EVALUATION

This is the final phase of the regression model where various performance metrics were highly utilized for evaluating the EInetRM model's performance. They are listed below in an elaborated manner.

Mean Squared Error (MSE)

It is the average of the squared differences between the predicted (\hat{y}_i) and the actual values (y_i).

$$MSE = \frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i)^2 \quad (17)$$

Root Mean Squared Error (RMSE)

It is the square root of the average of the squared differences between the predicted and the actual values.

$$RMSE = \sqrt{MSE} \quad (18)$$

Normalized Root Mean Squared Error (nRMSE)

It differs from the RMSE metric that normalizes the RMSE by dividing it by the range of the target variable. This normalization allows for comparing the performance of the models on the datasets with different scales.

$$nRMSE = \frac{RMSE}{\max(y) - \min(x)} \quad (19)$$

Mean Absolute Error (MAE)

It measures the average absolute differences between the predicted and the actual values. It provides the more interpretable measures of the average magnitude of errors.

$$MAE = \frac{1}{n} \sum_{i=1}^n |y_i - \hat{y}_i| \quad (20)$$

Mean Bias Error (MBE)

It is used to evaluate the bias or systematic error in a regression model. It measures the average difference between the predicted and the actual values. This metric does not provide the information about the spread or variability of errors, so it is often used in conjunction with other metrics like MAE or RMSE.

$$MBE = \frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i) \quad (21)$$

Median Absolute Percentage Error (MedAPE)

The metric measures the median of absolute percentage differences between predicted and actual values, providing a reliable measure of prediction accuracy, especially in the presence of outliers. It is scale-independent and suitable for comparing models across different datasets, allowing understanding of typical error magnitudes in terms of percentages of actual values.

$$MedAPE = \text{median} \left(\frac{|y_i - \hat{y}_i|}{|y_i|} \times 100 \right) \quad (22)$$

Absolute Percentage Error (MAPE)

It measures the average percentage error between the predicted and the actual values. A lower MAPE indicates better model performance.

$$MAPE = \frac{1}{n} \sum_{i=1}^n \left(\frac{|y_i - \hat{y}_i|}{|y_i|} \times 100 \right) \quad (23)$$

Mean Percentage Error (MPE)

This metric is used to evaluate the accuracy of predictions in a regression model. It measures the average percentage difference between the predicted and the actual values. It is similar to MBE which provides the information on whether the model tends to overestimate or underestimate the actual values.

$$MAPE = \frac{1}{n} \sum_{i=1}^n \left(\frac{y_i - \hat{y}_i}{y_i} \times 100 \right) \quad (24)$$

Symmetric Mean Absolute Percentage Error (SMAPE)

It addresses some of the limitations of other percentage-based metrics by providing a symmetric view of

the percentage errors that is not affected by the scale of the data. This metric is expressed as a percentage and it ranges from 0 to 200%. A lower the SMAPE score, better the performance of the model.

$$SMAPE = \frac{1}{n} \sum_{i=1}^n \frac{|y_i - \hat{y}_i|}{\left(\frac{|y_i| + |\hat{y}_i|}{2} \right)} \times 100\% \quad (25)$$

R-Squared metrics

R^2 metrics or the coefficient of determination used to evaluate the goodness of fit of a regression model. It is the widely used metric for prediction and regression models, but it has limitations such as its sensitivity to the number of predictors and inability to distinguish between the good and bad predictions in certain rare cases.

It represents the proportion of the variance in the dependent variable that is explained by the independent variables.

$$R^2 = 1 - \frac{\sum_{i=1}^n (y_i - \hat{y}_i)^2}{\sum_{i=1}^n (y_i - \bar{y})^2} \quad (26)$$

where, y_i is the actual values, \hat{y}_i is the predicted values and \bar{y} is the mean of actual values.

Adjusted R-Squared metrics

Adjusted R^2 is a metric that addresses the limitations of R^2 metrics by accounting for the number of predictors in a regression model. It penalizes the inclusion of unnecessary predictors that do not significantly improve the model, providing a more realistic measure of a model's explanatory power. This metric is particularly useful in preventing inflation of R^2 due to the inclusion of irrelevant predictors, making it a more accurate measure of a model's explanatory power.

$$\text{Adjusted } R^2 = 1 - \frac{(1 - R^2)(n-1)}{(n-p-1)} \quad (27)$$

where, R^2 is the regular R -squared, n is the number of observations and p is the number of predictors.

Explained Variance Score (EVS)

EVS is a metric that assesses the variance in dependent variables explained by a regression model, similar to R -squared metrics. It prioritizes the model's ability to capture target variable variability, considering both bias and variance of predictions. Its scale differs from R -squared metrics, ensuring a more accurate understanding of the model's performance.

$$EVS = 1 - \left[\frac{\text{var}(y - \hat{y})}{\text{var}(y)} \right] \quad (28)$$

where, y is the actual values, \hat{y} is the predicted values and var is the variance of actual values.

4.5. PERFORMANCE ANALYSIS

Table 1 Represents the lettuce yield prediction performance analysis using the improved EInetRM model with the help of number of distinct performance metrics.

Table 1. Performance Analysis of ElasticNet regression with other Regression methodologies

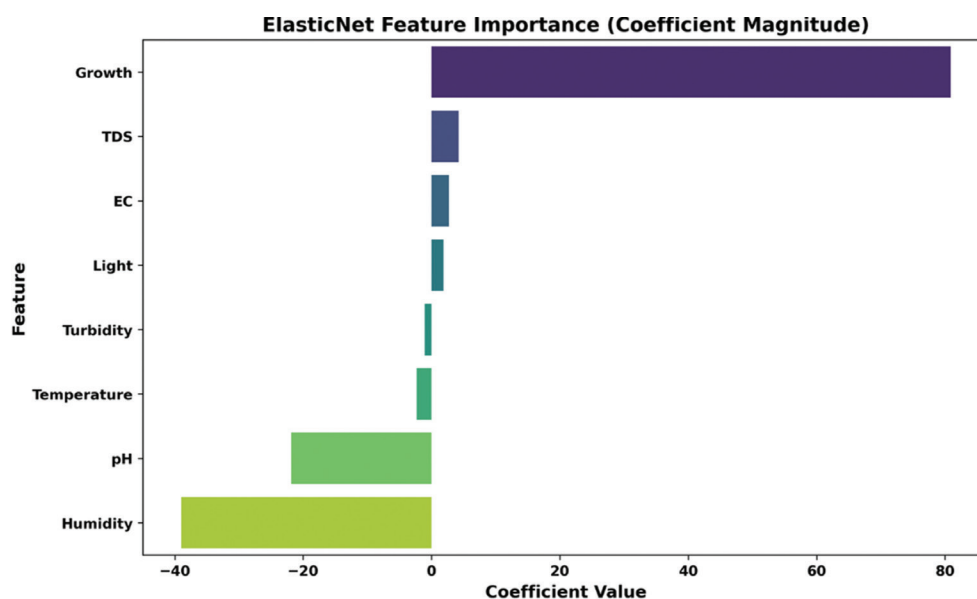
Regression Type	Performance Measurements											
	MSE	RMSE	nRMSE	MAE	MBE	MedAPE	MAPE	MPE	SMAPE	R-squared	Adjusted R-squared	EVS
Linear Regression	8.591	2.931	0.3094	7.667	0.58	4.85	4.20	1.41	46.332	0.89	0.90	0.721
Lasso Regression	8.640	2.94	0.3012	7.64	0.47	4.15	4.07	1.27	43.076	0.84	0.85	0.703
Ridge Regression	8.591	2.931	0.2012	6.73	0.40	4.03	4.07	1.63	41.375	0.87	0.88	0.83
Support Vector	7.246	2.691	0.1922	6.67	0.406	4.026	4.06	1.59	41.026	0.88	0.89	0.8256
Random Forest	6.875	2.622	0.1568	6.49	0.391	4.006	3.99	1.48	40.368	0.90	0.906	0.854
ElasticNet regression	5.239	2.288	0.1015	6.24	0.38	3.92	3.74	1.04	39.51	0.91	0.92	0.88

The use of the EInetRM in predicting lettuce production in controlled indoor aeroponic environments produced valuable findings in this carried out research. The Mean Squared Error (MSE) of 5.239 is the average of the squared differences between the predicted and actual yields. The Root Mean Squared Error (RSME) of 2.288, calculated as the square root of the Mean Squared Error (MSE), represents the standard deviation of the residuals and indicates the accuracy of the model. The NRMSE of 0.1015 indicated the model's high accuracy in predicting the yield range. The Mean Absolute Error (MAE) of 6.24 is the average absolute difference between the predicted and actual values, serving as a concise measure of the model's performance. The model's predictions showed a small Mean Bias Error (MBE) of 0.38, indicating a minor tendency to underestimate. The investigation also found a Median Absolute percentage Error (MedAPE) of 3.92, indicating that the minimum number of the predictions differed from the actual values by this proportion. The Mean Absolute Percentage Error (MAPE) of 3.74 indicates the average percentage difference, while the Mean Percentage Error (MPE) of 1.04 suggests a tiny value of underestimate. The Symmetric Mean Absolute Percentage Error (SMAPE) of 39.51 represented a measure of symmetric percentage difference where, this minimum symmetric

error showcases the better training and testing of the model on the data. The R-squared value of 0.91 demonstrates a strong correlation between the model and the real data, indicating its strength on lettuce yield prediction. The EInetRM demonstrated resilience, as shown by its Adjusted R-squared value of 0.92, which takes into account the number of predictors. In addition, the Explained variance Score (EVS) of 0.88 accurately quantified the amount of fluctuation in lettuce production that was successfully accounted for by the EInetRM. In conclusion, these results collectively suggest that the EInetRM stands out as a promising and accurate approach for predicting indoor aeroponic lettuce yield, substantiated by a comprehensive evaluation of diverse metrics.

4.6. FEATURE IMPORTANCE VISUALIZATION

The visualization of feature importance for the proposed research work has been represented using the Coefficient bar plot which is useful when many number of input features were being utilized for predictions. Here, from the plot we can observe and interpret the most influential variables that affects the growth of lettuce crop based on the positive (bars >0) and the negative impact (bars <0) as represented in Fig. 9.

**Fig. 9.** Coefficient magnitude diagram of input variables

4.7. PREDICTION GRAPH

In the context of aeroponic lettuce yield prediction by the improved ElnetRM model, the prediction graph as represented in Fig. 10. highlights the efficiency of utilizing the regression model using the scatter plot.

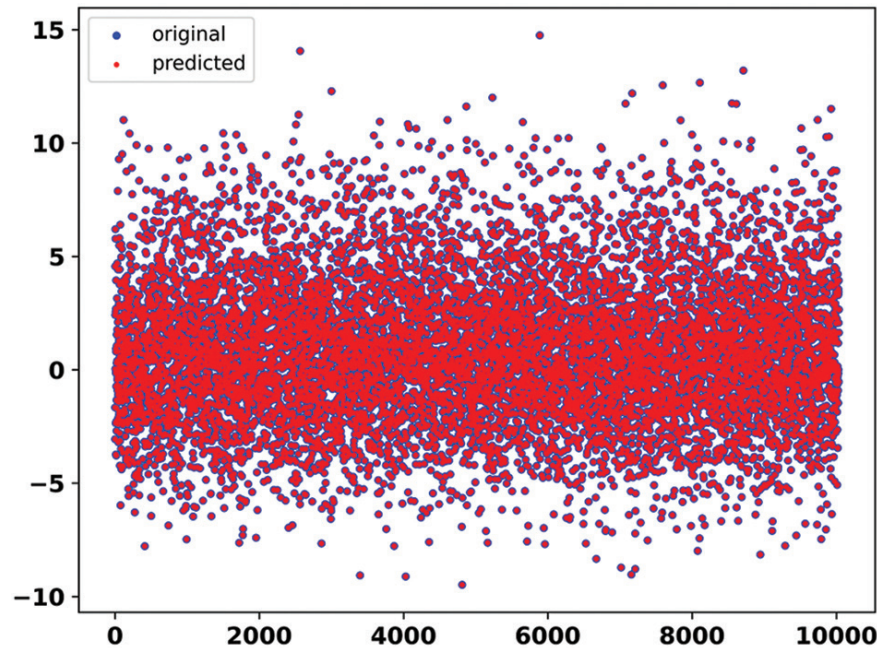


Fig. 10. Lettuce Yield Prediction Graph (Scatter Plot)

The blue line in the prediction graph represents the original values or the actual values (input parameters) of the lettuce dataset and the other color represents the predicted values (lettuce yield in weights) by the ElnetRM model. As the predicted values overlaps with the actual values, the successful prediction by the model is highly depicted while the small discrepancies highlight the areas of further improvement in the prediction process.

5. CONCLUSION AND FUTURE SCOPE

Ultimately, this research work evaluates the Elastic Net machine learning regression model's effectiveness in accurately forecasting lettuce production in indoor aeroponic systems. The model effectively handles the complex dynamics of indoor aeroponic settings, addressing multicollinearity and balancing sparsity and variable relevance. The results show superior performance compared to conventional models like linear regression and Ridge regression. The model's interpretability enhances its usefulness by providing valuable insights for decision-making in indoor aeroponic lettuce growth. The study also contributes to precision agriculture knowledge by highlighting the special benefits of Elastic Net in indoor aeroponic systems. The findings have practical applications for farmers, agronomists, and researchers involved in enhancing agricultural yield in controlled settings.

The Future research should focus on fine-tuning parameters, integrating additional variables, dynamic model adaptation, ensemble approaches, practical im-

plementation, and extension to other crops. The model's performance can be improved by incorporating environmental and nutrient variables and advanced sensor data. On-farm trials and validations should assess the model's feasibility in real-world indoor aeroponic farming scenarios. The ongoing exploration and refinement of machine learning models will contribute to precision farming, resource utilization, and sustainable food production.

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